

Errata:

Robust Detection of Shady and Highlighted Roads for Monocular Camera Based Navigation of UGV

July 9, 2011

We apologize for a typographical error in page 6, equation 33: misbalanced parentheses. Correct equation is

$$D(\mathbf{p}, \boldsymbol{\mu}_i) = \min_i ((\mathbf{p} - \boldsymbol{\mu}_i)^T \boldsymbol{\Sigma}_i^{-1} (\mathbf{p} - \boldsymbol{\mu}_i)) \quad (33)$$

Sorry for any inconvenience.